

# THE INFLUENCE OF CREW VARIABILITY WHEN USING HIGH RESOLUTION TOPOGRAPHIC SURVEYS TO MONITOR INSTREAM HABITAT: A case study from the Columbia River basin

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## 1. INTRODUCTION

The goal of the Columbia Habitat Monitoring Program (CHaMP) is to implement a standardized fish habitat monitoring program in watersheds with Endangered Species Act (ESA)-listed steelhead and Chinook populations of the Interior Columbia River Basin. The CHaMP protocol is composed of methods that capture topographic, substrate, riparian vegetation, large woody debris and fish cover features of spatially balanced locations within each watershed. Topographic data is captured using total stations and methods incorporating surveying both channel unit boundaries and topographic features affording DEM and bathymetric mapping of sample sites (Bouwes et al., 2011). DEMs will be used to monitor habitat and geomorphic changes at high spatial resolution through time.

In the summer of 2011 the CHaMP program concluded its pilot field season where 12 crews from 8 agencies and organizations sampled 325 sites within 10 watersheds. Like any monitoring campaign that might rely on different crews, either between years or among sites, CHaMP suffers from knowing whether calculated differences are real or due to noise from discrepancies in how the different crews sampled. To discern the extent of crew variability a study was conducted to intercompare topographic surfaces derived by different crews.

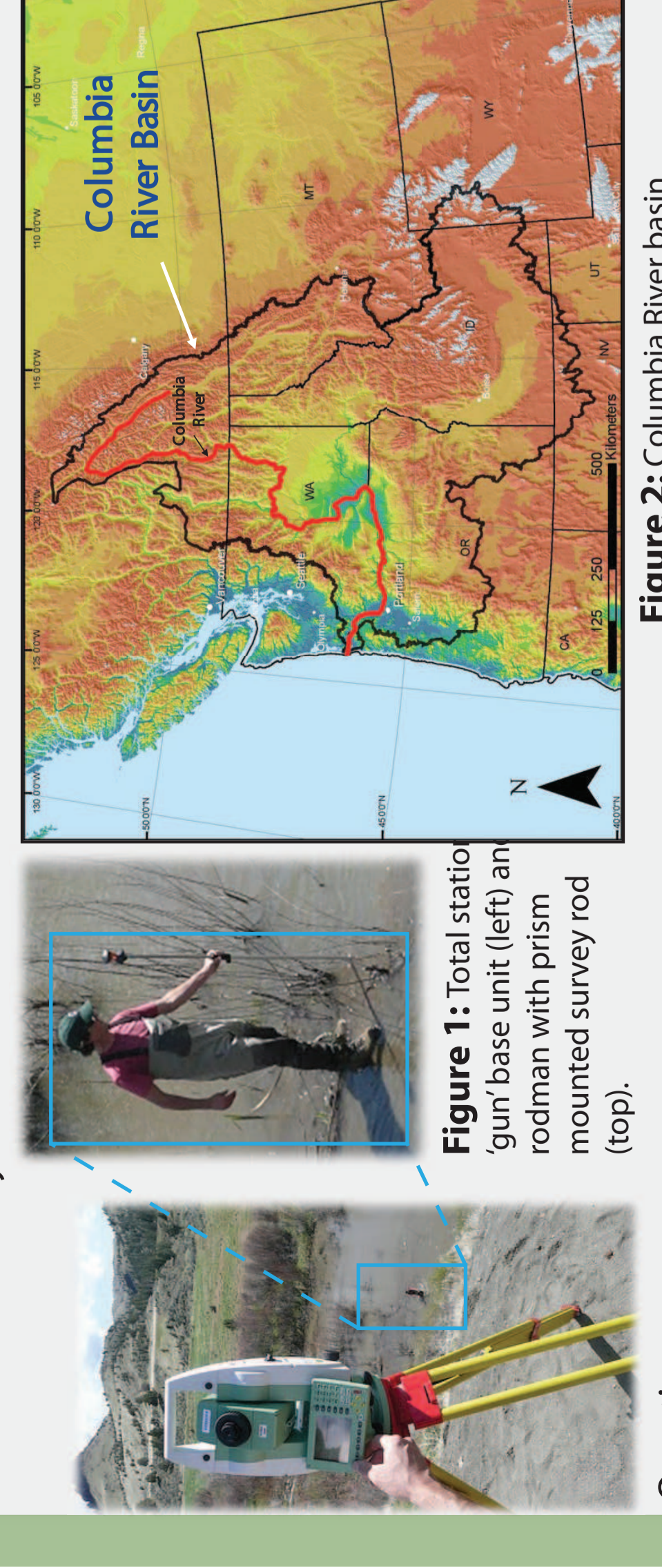


Figure 1: Total station 'gun' base unit (left) and mounted survey rod (top).

Figure 2: Columbia River basin

Questions:

- To what extent can large observed differences between crews be attributed to systematic surveying and processing errors?
- At specific sites, how does crew variability influence the quality of the data collected?
- To what extent does crew variability limit our ability to:
  - Reliably calculate DEM derived metrics such as water depth?
  - Detect and interpret geomorphic changes from time series data?

## 2. STUDY SITE DESCRIPTION

Seven crews sampled the same six stream reaches in the Upper Grande Ronde River basin of Northeast Oregon (Figure 2). The Grande Ronde River flows in a northeasterly direction to its confluence with the Snake River. The basin encompasses 4238 km<sup>2</sup>, has a mean elevation of 1267 m and a mean annual precipitation of 719 mm. The six sample reaches selected include 3 smaller lower order sites and 3 larger mainstem sites (Table 1).

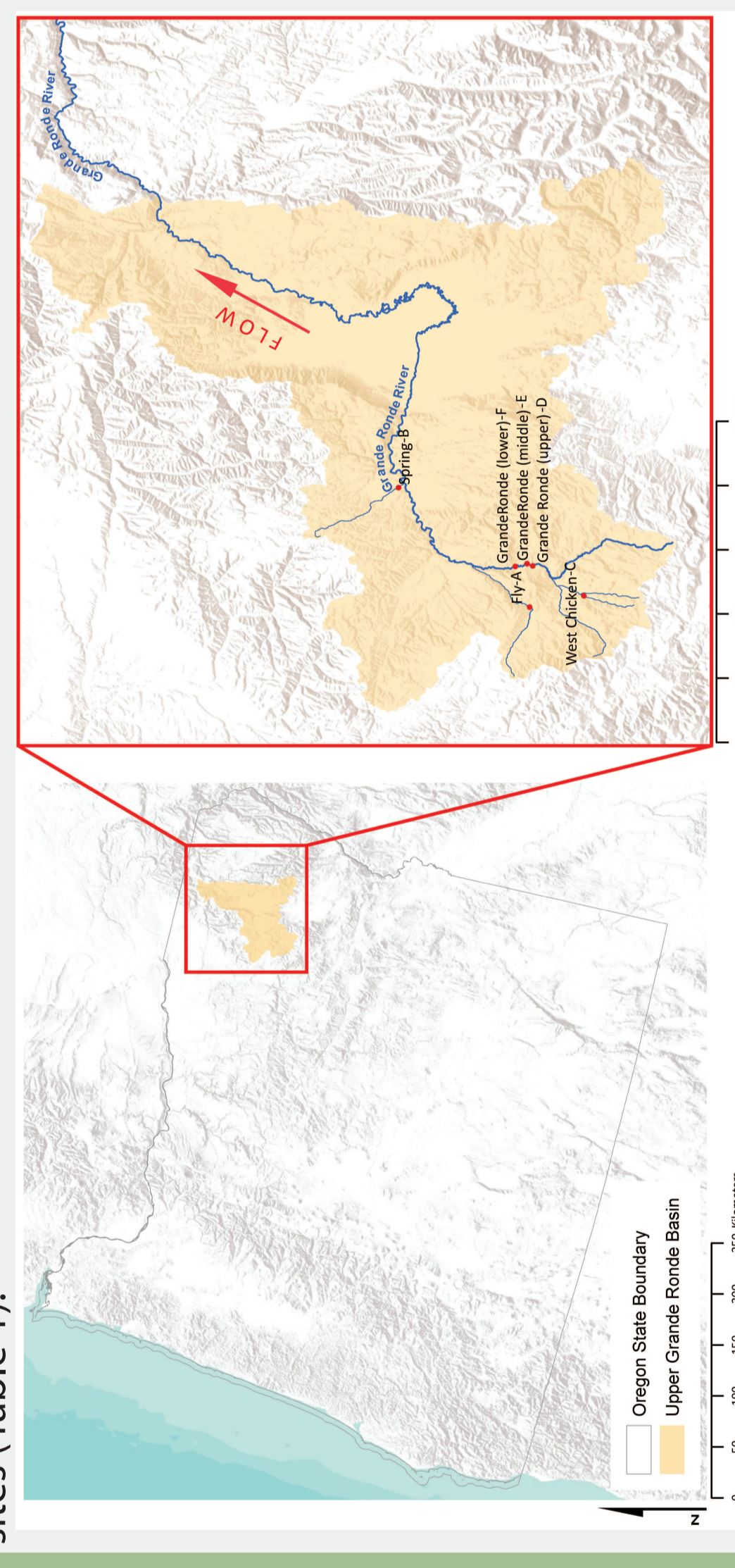


Figure 3: Upper Grande Ronde River watershed and study site locations.

Stream Name	Elevation (m)	Gradient (%)	Site Characteristic	
			Primary bedform class	Average bankfull width (m)
A. Fly Creek	1311	0.92	Pool-riffle	7.2
B. Spring Creek	1233	1.92	Pool-riffle	5.9
C. Spring Creek	1233	1.92	Pool-riffle	5.9
D. Grande Ronde River (upper site)	1206	1.14	Plane-Pool	16.8
E. Grande Ronde River (middle site)	1187	3.00	Step-Pool	36.0
F. Grande Ronde River (lower site)	1155	1.00	Pool-riffle	32.0

Table 1: Sample site characteristics



## 3. STUDY METHODS

### Survey Methods

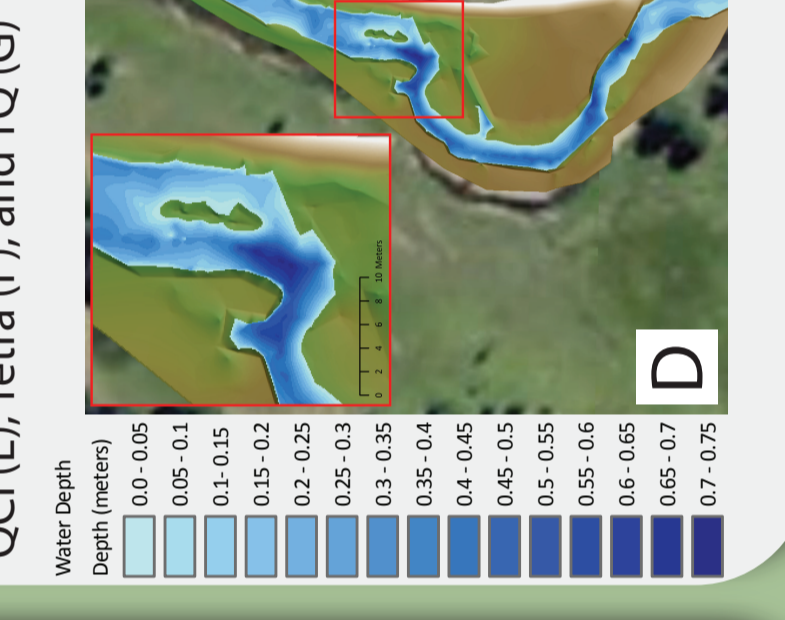
- Crews followed the CHaMP protocol (Bouwes et al., 2011) using total station surveys (Figures 1 & 4)
- Crews were responsible for QA/QC, building and editing TINs and DEMs
- Also delineated habitat units, measured substrate, canopy cover, riparian vegetation and pool tail fines.

### Analysis Methods

- Raster max-min analysis to quantify maximum range of crew variability
- Spatially variable estimate of DEM error using Fuzzy Inference System (FIS; Table 4) developed by Wheaton et al. (2010)
- Calculated the coefficient of variation (StdDev/Mean) to allow comparison between data sets with different units and widely different means.
- Modeled potential geomorphic change scenario using Geomorphic Change Detection (GCD) software

Figure 4: Example from CHaMP protocol showing channel view from the channel view showing the location of toe of bank and top of bank breaklines.

Figure 5: Example of crew variability in DEM-derived water depth rasters from Fly Creek. CRITFC (A), ELR (B), ODFWJ (C), ODFWUGR (D), OCCI (E), Tetra (F), and TQ (G)



## 4. SURVEY & PROCESSING ERRORS

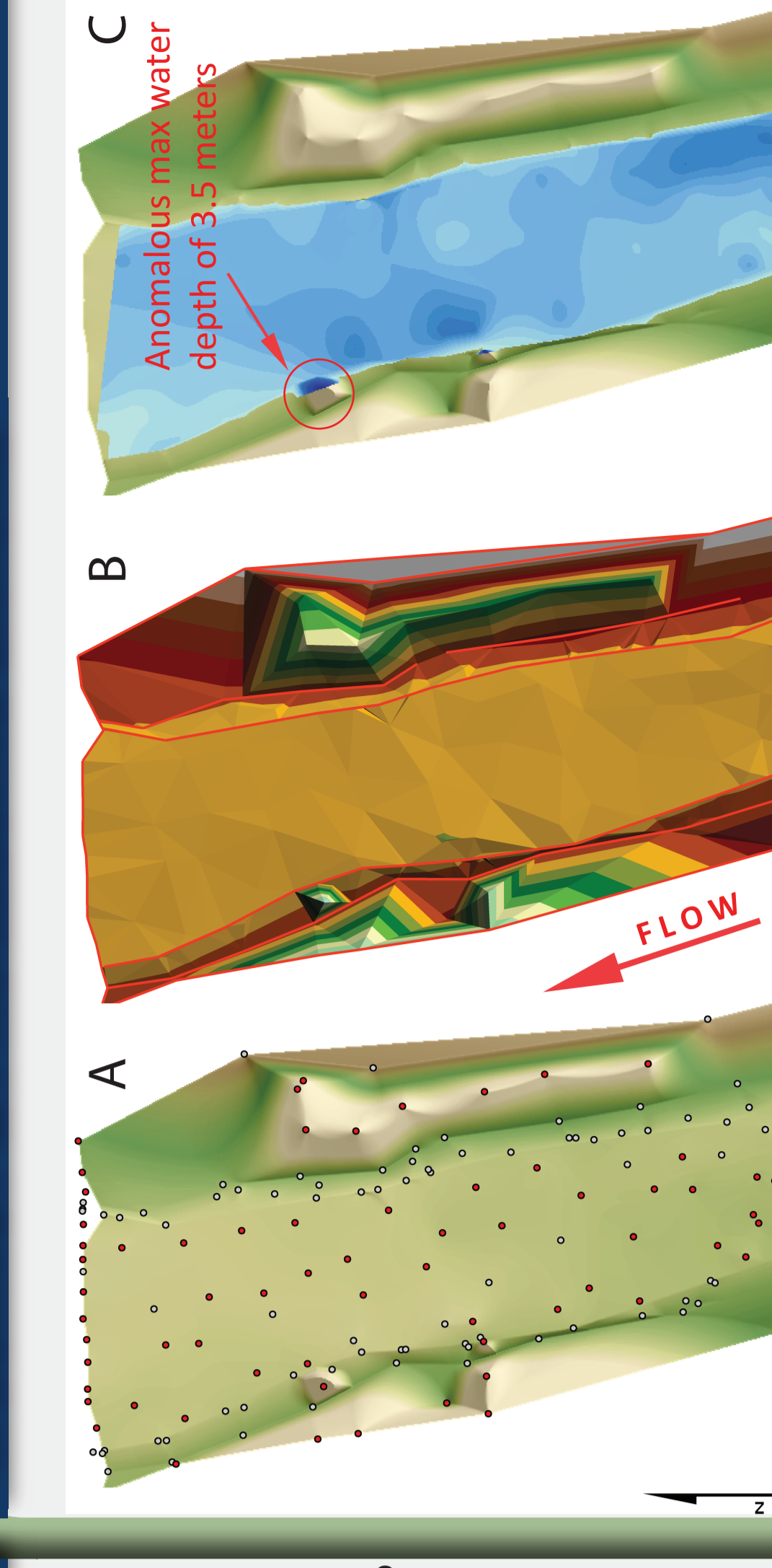


Figure 6: Example of a survey error by ODFWUGR crew at the Grande Ronde River upper site. Here, we inferred that while collecting topo coded points the crew incorrectly recorded the total station rod height (A). This led to TIN busts (B) that were not caught or corrected by the crew member who post-processed and edited the TIN. One of the RL TIN busts fell within the wetted channel and resulted in a localized anomalous 3.5 meter water depth (C) in the derived bathymetric raster.

### TAKE HOME:

- Most common errors were TIN busts not caught by crews when editing TINs. These were typically associated with incorrect rod heights.
- Most observed errors are easy to fix post-hoc (e.g. TIN bust). Some are difficult or nearly impossible to remedy post hoc and could compromise an entire survey (e.g. excessive error in a BS check).
- All observed errors are easy to avoid with clear guidance and training.

Survey Problems	Crew					
	CRITFC	ELR	ODFWJ	ODFWUGR	OCCI	Tetra
TIN Problems	1	1	1	1	1	1
BS Check Problems	1	1	1	1	1	1
Post-processing Problems	1	1	1	1	1	1
Way to Remedy	Difficult/impossible to remedy	Difficult/impossible to remedy	Difficult/impossible to remedy	Difficult/impossible to remedy	Difficult/impossible to remedy	Difficult/impossible to remedy

Table 2: Summary of survey and post-processing issues.

## 5. RESULTS: RANGE OF VARIABILITY & SURFACE QUALITY

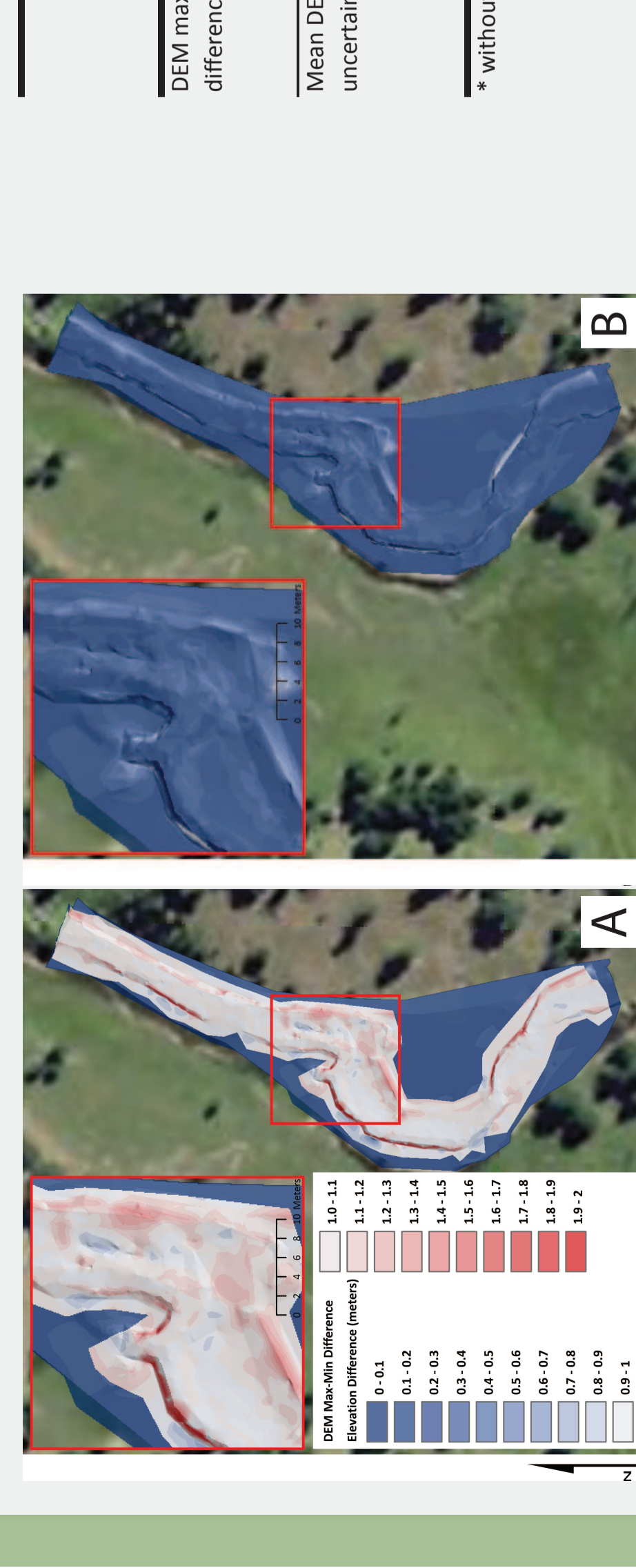


Figure 7: Fly Creek DEM maximum-minimum difference raster with (A) and without ELR crew (B) who made survey error of adding 1 meter to total station instrument height.

Rule:	Slope	Pr. $\rho$	$\delta(z)$	Output
	%		pts/m <sup>2</sup>	m
1	Low	Low	Average	Low
2	Low	Medium	Low	Low
3	Low	High	Low	Low
4	Medium	Low	High	High
5	Medium	Medium	High	High
6	Medium	High	High	High
7	High	Medium	High	High
8	High	High	High	High

Table 4: FIS slope and point density rule set

### TAKE HOME:

- The range of variability among crews is within typical estimates of DEM error for total stations
- Variability is least in the wetted channel (i.e. the primary fish habitat) & worse on the margins and out of channel areas
- FIS should be calibrated for lower point density surveys & adjusted to account for breaklines

## 6. RESULTS: EFFECT OF CREW SURVEY VARIABILITY ON DEM DERIVED WATER DEPTH RASTERS

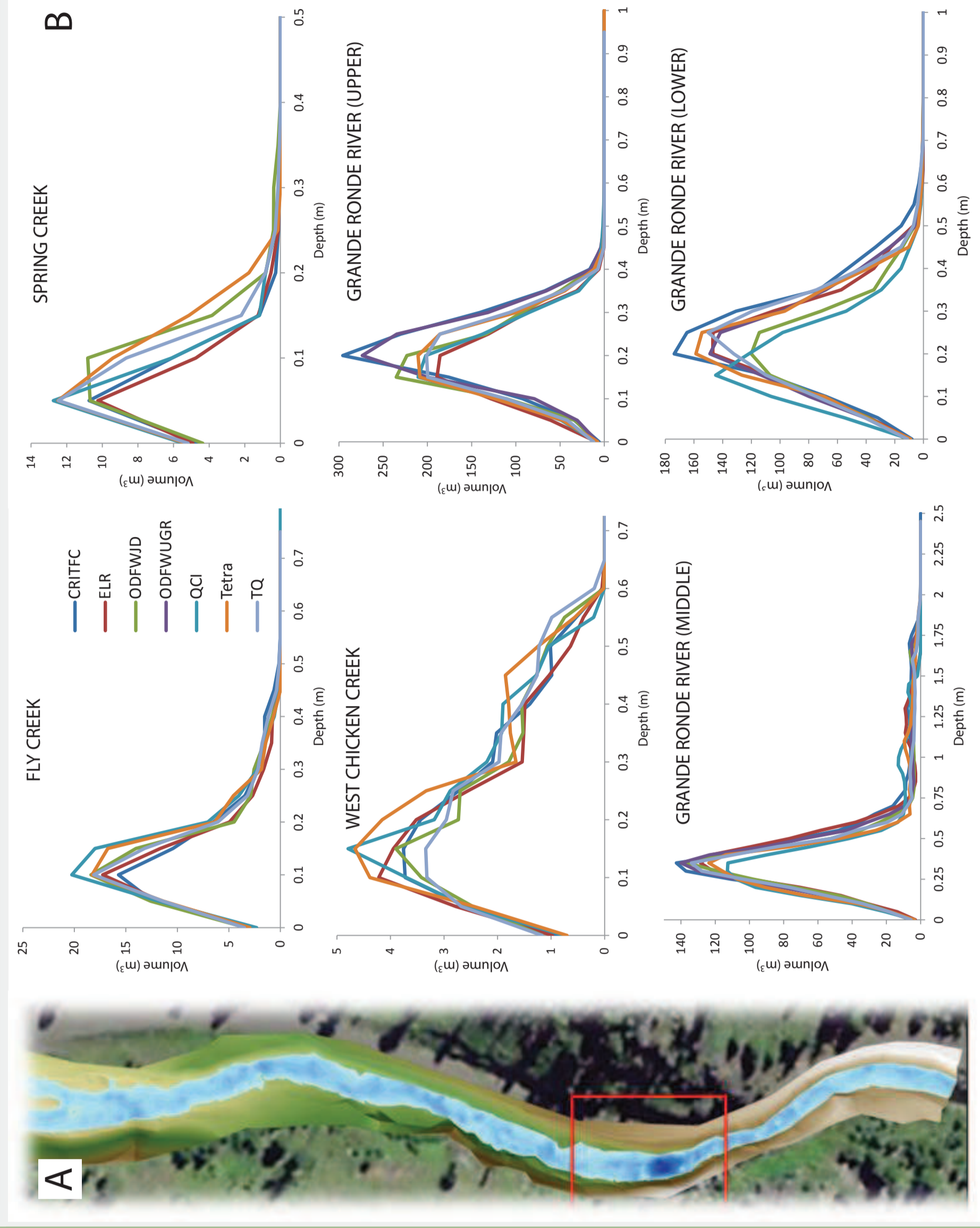


Figure 10: Example of a DEM-derived water depth raster from Grande Ronde River middle site (A). Water depth frequency distribution for all crews by site (B).

- At the lower order sites, average water depths vary by up to 3 cm while maximum water depth varies by up to 3.14 m. CV values are relatively similar between crews at all sites indicating water depths vary by a up to 4 cm while maximum water depth varied by up to 3.14 m. CV values are relatively similar between crews at all sites indicating water measured comparable variation of depths. This is also reflected in the depth frequency distributions (Figure 10B).
- Depth frequency distribution plots (Figure 10B) indicate DEM-derived water depth is not overly sensitive to highly localized differences among crews.

Site	WATER DEPTH RASTERS					
	CRITFC	ELR	ODFWJ	ODFWUGR	OCCI	Tetra
Statistic	Min (m)	0.56	0.51	0.43	0.72	0.53
	Max (m)	0.11	0.11	0.11	0.12	0.11
	Mean (m)	0.12	0.12	0.12	0.12	0.12
	StdDev (m)	0.03	0.03	0.03	0.03	0.03
	CV (%)	21.26	21.26	21.26	21.26	21.26
	Min (m)	0.38	0.39	0.40	0.33	0.34
	Max (m)	0.04	0.04	0.05	0.04	0.05
	Mean (m)	0.04	0.04	0.05	0.04	0.05
	StdDev (m)	0.01	0.01	0.01	0.01	0.01
	CV (%)	25.00	25.00	25.00	25.00	25.00
	Min (m)	0.00	0.00	0.00	0.00	0.00
	Max (m)	0.16	0.15	0.14	0.25	0.16
	Mean (m)	0.12	0.11	0.12	0.12	0.12
	StdDev (m)	0.02	0.02	0.02	0.02	0.02
	CV (%)	17.42	17.42	17.42	17.42	17.42
	Min (m)	0.53	0.48	0.50	0.32	0.60
	Max (m)	0.21	0.17	0.18	0.20	0.18
	Mean (m)	0.21	0.17	0.18	0.20	0.18
	StdDev (m)	0.09	0.08	0.09	0.09	0.08
	CV (%)	42.86	42.86	42.86	42.86	42.86
	Min (m)	2.05	1.66	1.92	1.92	1.67
	Max (m)	0.33	0.30	0.31	0.29	0.30
	Mean (m)	0.33	0.30	0.31	0.29	0.30
	StdDev (m)	0.04	0.04	0.04	0.04	0.04
	CV (%)	69.67	69.67	69.67	69.67	69.67
	Min (m)	0.82	0.66	0.88	0.93	0.88
	Max (m)	0.00	0.00	0.00	0.00	0.00
	Mean (m)	0.00	0.00	0.00	0.00	0.00
	StdDev (m)	0.00	0.00	0.00	0.00	0.00
	CV (%)	53.05	53.05	53.05	53.05	53.05

Table 6: Summary DEM derived water depth rasters for each crew at each site, summarized across all crews at each site and for the three lower order sites and mainstem sites.

## 7. RESULTS: ABILITY TO DETECT GEOMORPHIC CHANGE

Of the many metrics CHaMP data can be used to estimate, geomorphic change detection is potentially one of the most sensitive to crew variability and the quality of the topographic data. As this is only the first year of data collection in CHaMP, repeat topographic surveys were not available that captured real geomorphic change. As such, we created an artificial DEM that represented a plausible future state of the channel. An obvious change scenario was modeled whereby a beaver builds a dam between Time 1 and 2, with a subsequent flood resulting in channel avulsion. We hypothesized that all crews should be able to detect this change, regardless of crew variability because the magnitude of the signal exceeded likely DEM uncertainties. Each individual crew's DEM was used as Time 1. The ODFWUGR DEM was selected as truth and used to model potential change (i.e. Time 2 surface).

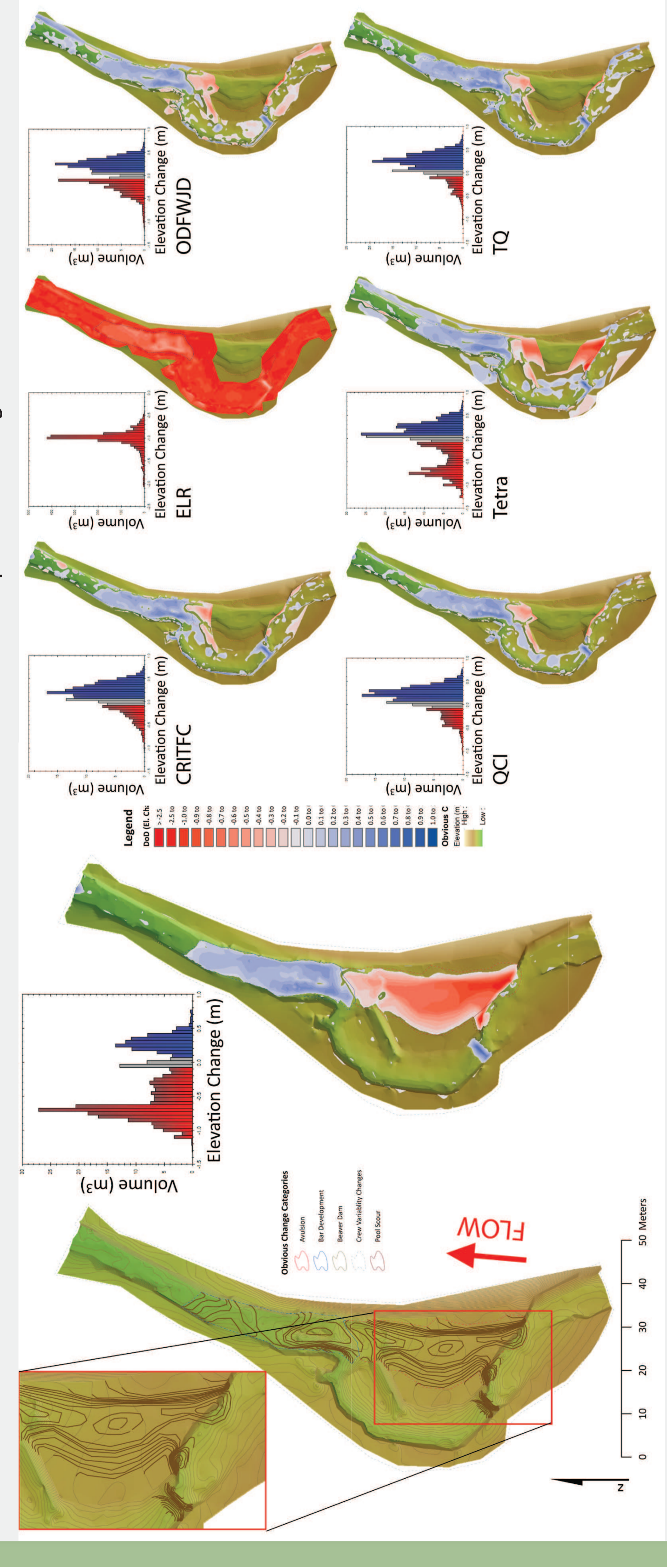


Figure 11: Results of modeled geomorphic change of Time 2 - Time 1. Here the ODFWUGR crew represents 'true' change. Time 2 and 1 surfaces were while areas in red represent erosion. Histograms represent gross volumetric differences.

## 8. CONCLUSIONS

- Crews collected topographic data of sufficient quality and consistency that their DEMs and water depths show the same basic spatial patterns. Additional guidance on point densities and breakline data collection could help promote higher qualities and consistency.
- The largest observed differences among crews were attributed to a systematic error by one crew (different crews across sites). Most systematic errors are easy to identify and remedy in the data editing or QA/QC process (e.g. TIN busts). These errors are also easy to avoid with more targeted training and QA/QC procedures.
- Survey extent matters, particularly with long term datasets and ability to detect geomorphic change. The topographic data among crews was of adequate quality to support geomorphic change detection for both obvious changes (reported) and subtle changes in the channel and along channel margins. However, crews were not given adequate guidance on how far to extend their survey extents out into areas that the channel could plausibly migrate into. These floodplain areas can generally be surveyed with minimal effort to facilitate a more accurate portrayal of future geomorphic changes.
- Total stations are tried and true and most versatile (in CHaMP context), but not necessarily the most efficient at individual sample reaches

## 9. REFERENCES

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Wheaton, J.M., Brasington, J., Darby, S.E., Sear, D.A., 2010. Accounting for uncertainty in DEMs from repeat topographic surveys: improved sediment budgets. Earth Surface Processes and Landforms, 35(2), 136-156.

## 10. ACKNOWLEDGEMENTS

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